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In LiDAR, laser light is sent from a source (transmitter) and reflected from objects in the scene. The reflected light is detected by the system receiver and the time of flight (TO) $T_j = T^* + BT / F$

What is LiDAR and How Does it Work? - Synopsys : glossary : what-is-lidar

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The object-wise feature extractors project LiDAR point clouds into 2D representations and generate the object proposals using 2D networks. Then, they regress the region proposals to predict the 3D bounding boxes.

A Survey on Deep-Learning-Based LiDAR 3D Object Detection for ...

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It is a Continuity reboot. That means some of the same character

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